# 8 Data Recording

# 8.1 In Brief

A wide variety of operating modes permit flexible configuration of drive and automation systems by using positioning, speed and current regulation. The built-in EtherCAT interface allows networking to multiple axes drives as well as online commanding by EtherCAT master units.

EPOS3 EtherCAT features a built-in data recorder to debug errors and to monitor motion control parameters and actual values.

#### 8.1.1 Objective

The present Application Note explains the functionality of the built-in data recorder. Features and configuration options are explained.

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#### 8.1.2 Scope

Hardware	Order #	Firmware Version	Reference
EPOS3 EtherCAT		2200h	Firmware Specification
EPOS3 70/10 EtherCAT	411146	2200h or higher	

 Table 8-74
 Data Recording – covered Hardware and required Documents

#### 8.1.3 Tools

Tools	Description
Software	«EPOS Studio» Version 2.00 or higher

Table 8-75 Data Recording – recommended Tools

Data Recording Overview

# 8.2 Overview

# 8.2.1 Launching the Data Recorder

- 1) Start «EPOS Studio».
- 2) Start Data Recorder either click right ¤Selected Node¤ or click ¤Tools¤ in Navigation Window.
- 3) Following screen will be displayed:



Figure 8-75 Data Recorder Overview

#### 8.2.2 Control Elements and their Function

**Title Bar** 

Control Element	Description / Function		
Status	Displays data recorder's status. The following states are possible:		
	Data Recorder Running Continuous Acquisition Mode	Data are continuously recorded and displayed.	
	Data Recorder Waiting Single Trigger Mode	On standby, waiting to receive a trigger to start a single data record (for trigger options $\rightarrow$ page 8-96).	
	Data Recorder Triggered Single Trigger Mode	Sampling in process until data buffer is full.	
	Data Recorder Stopped Single Trigger Mode or Continuous Acquisition Mode	Recording completed and stopped, results are being displayed.	
Start	Commences sampling. In "Single Trigger Mode", the data recorder is waiting for a trigger. In "Continuous Acquisition Mode", the data recorder is continuously recording and displaying data.		
Stop	Stops sampling. Latest recorded data are being displayed.		
Force trigger	A trigger has been activated.		
Table 8-76 Data	a Recording – Title Bar		

# **Options Bar**

Control Element	Description / Function	
Display Mode	Linear Mode	To display data, linear interpolation will be used.
	Sample & Hold	Between samples, no interpolation will be used.
Available Curves	Available curves will be listed. Tick check box to show/untick to hide a curve in the display.	
Cursor	Off	No curser will be displayed.
	Free Cursor	Curser will appear, as soon as the mouse is moved.
	Attached Cursor	Moving the mouse will attach the cursor to the selected curve. Use "Available Curves" to select another curve.
Update Display	Last sampled data will be loaded and displayed.	
Configure Recorder	To select sampled data and to configure the data recorder (→ "Data Recorder Configuration" on page 8-94).	

 Table 8-77
 Data Recording – Option Bar

# Display

Control Element	Description / Function
Zoom	<ul> <li>Zoom in: Click left and draw a rectangle over desired area – status indication (upper left corner) will change to "Zoomed".</li> <li>Zoom out: Click right – status indication will disappear.</li> </ul>
Cursor	If activated, the cursor will appear as small circle. Cursor's actual coordinates are displayed in the upper right corner.
Left / Right Scale	Each data set may be displayed in either left or right pane ( $\Rightarrow$ Data Recorder Configuration).
Time Scale	At bottom border with corresponding time base at lower right corner.
Legend	Currently displayed curves' legend appears in lower left corner.

Table 8-78 Data Recording – Display

## Data Recording Data Recorder Configuration

#### **Context Menu**

Control Element	Description / Function			
Load Recorded Data	Load recorded data from file (*.rda).			
	Save recorded data to file in	Save recorded data to file in following file formats:		
	*.rda	Binary Format (for use with «EPOS Studio»)		
Save & Export	*.txt	ASCII Text Format (for import in Microsoft Excel)		
Recorded Data	*.CSV	Comma Separated Values (for import in Microsoft Excel)		
	*.bmp	Bitmap Format		
Auto Scale	Select this option to automatically calculate optimal scale values.			
Setup Scale Values	If "Auto Scale" is deselected, left/right pane and time scale can be defined manually.			
Manual	Open connected device's online help manual.			
Configure Recorder	To select sampled data and to configure data recorder (→Data Recorder Configuration).			
Table 8-79 Dat	a Recording – Context Menu			

# 8.3 Data Recorder Configuration

Configure Recorder			? 🗙
Channel 1 Channel 1 Active Variable Size Variable Size Channel 1 Variable Size	on Demand Value d 32-Bit ft Scale	Data Sampling Total Time Sampling Period Samples	128 mill/Seconds 1 mill/Second 128
Channel 2 Channel 2 Active Variable Size Channel 2 Variable Size Channel 2 Channel 2 C	on Actual Value d 32-Bit ft Scale Right Scale	C Total Time Trigger Configura C Continuou © Single Trig	e 🗭 Sampling Period tion s Acquisition Mode iger Mode
Channel 3 Channel 3 Inactive Variable Size Channel 3 Variable Size Channel 3 Variable Channel 3 Variable Channel 3	mental Encoder 1 Counter		vement Trigger or Trigger jital Input Trigger d of Profile Trigger
Channel 4 Channel 4 Inactive Variable Size Unsig C Lef	mental Encoder 1 Counter	Preceding Samples	s 10 milliSeconds
ОК	Cancel Help	0% 25%	50% 75% 100%

Figure 8-76 Data Recording – "Configure Recorder" Dialog

# Channel 1...4

Control Element	Description / Function
Channel Active/ Inactive	Activate/deactivate up to four recorder channels.
Variable	Select desired variables to be recorded.
Variable Size	Displays size of selected variable.
Left / Right Scale	Select pane to display the recorded data.
Table 8-80 "Cor	nfigure Recorder" – Channel

# **Data Sampling**

Control Element	Description / Function
Total Time	Displays total duration.
Sampling Period	Select sampling period.
Samples	Displays number of samples per channel.
Total Time or Sampling Period	Select whether to determine the total time or the sampling period.

# Table 8-81 "Configure Recorder" – Data Sampling

# **Trigger Configuration**

Control Element	Description / Function	
Continuous Acquisition Mode	Data will continuously be recorded.	
Single Trigger Mode	Movement Trigger	A trigger is activated upon every start of a movement.
	Error Trigger	A trigger is activated upon an occurring error.
	Digital Input Trigger	A trigger is activated at an edge of a digital input. <b>Note:</b> In "Homing Mode", also the current threshold will be interpreted as a trigger.
	End of Profile Trigger	A trigger is activated at the end of a movement profile.

 Table 8-82
 "Configure Recorder" – Trigger Configuration

# **Trigger Time**

Control Element	Description / Function
Preceding Time	The lead time to be displayed prior activation of a trigger. "100%" permits display of data prior the trigger. <b>Best Practice:</b> Use the trigger time in combination with the error trigger to debug errors.
Preceding Samples	Displays the number of samples before the trigger.

 Table 8-83
 "Configure Recorder" – Trigger Time

#### Data Recording

Example: Data Recording in "Profile Position Mode"

# 8.4 Example: Data Recording in "Profile Position Mode"

# 8.4.1 Step 1: Configure Data Recorder

1) Click ¤Configure Recorder¤ in the options bar or select ¤Configure Recorder¤ from the context menu.

	Load Recorded Data Save & Export Recorded Data	
~	Auto Scale Setup Scale Values	Configure Recorder
	Configure Recorder	
0	Help 6	

Figure 8-77 Configure Data Recorder

- 2) Select the following variables:
  - Position Demand Value
  - Position Actual Value
  - Velocity Actual Value
  - Current Actual Value
- 3) Select a sampling period of 1 ms.
- 4) Select ¤Single Trigger Mode¤ and tick ¤Movement Trigger¤.
- 5) Select a preceding time of 0 microseconds.

Channel 1		Data Sampling
Chappel 1 Variable	Position Demand Value	Total Time 73 milliSeconds
Active Variable Siz	signed 32-Bit	Sampling Period 1 millSecond
	Ceft Scale C Right Scale	Samples 73
Channel 2		C Total Time 📀 Sampling Period
Channel 2 Variable	Position Actual Value	Trigger Configuration
Active Variable Siz	Signed 32-Bit	C Continuous Acquisition Mode
	Left Scale C Right Scale	<ul> <li>Single Trigger Mode</li> </ul>
Channel 3		Movement Trigger
Variable	Velocity Actual Value	Digital Japant Triager
Channel 3 Variable Active Variable Siz	Signed 32-Bit	End of Profile Trigger
y venebic siz	C Laft Scale @ Bight Scale	
	S Lert Stale 19 Right Stale	Trigger Time
Channel 4		Preceding Time 0 microSeconds
Channel 4 Variable	Current Actual Value	Preceding Samples 0
Active Variable Siz	signed 16-Bit	
	C Left Scale	

Figure 8-78 Select Configuration Options

6) Click ¤OK¤ to save settings.

Data Recording

Example: Data Recording in "Profile Position Mode"

#### 8.4.2 Step 2: Execute Movement

- 1) Change the active view to "Profile Position Mode".
- 2) Activate "Profile Position Mode".
- 3) Enable the EPOS3 70/10 EtherCAT and start a relative movement.

Operation Mode					
Active Operation Mode	ProfilePosition Mode		Activate Profile Posi	tion Mode	
Profile			Parameters		
Target Position	500	qc	Min Position Limit	-2147483648	qc
Profile Type	Trapezoidal 💌		Max Position Limit	2147483647	qc
Profile Velocity	1000	rpm	Max Profile Velocity	2000	rpm
Profile Acceleration	10000	rpm/s	Max Following Error	2000	qc
Profile Deceleration	10000	rpm/s	QuickStop Deceleration	10000	rpm/s
			Actual Values		
			Position Actual Value	500	qc
			Position Demand Value	500	qc
The EPOS is					
enabled	Move Absolute				
Help	Move Relative	1	Halt		

Figure 8-79 Execute Movement

#### 8.4.3 Step 3: Update Display

Change back to the view "Data Recording". If the display does not automatically refresh, press ¤Update Display¤ button.

#### 8.4.4 Step 4: Save recorded Data

1) Click right ¤Save & Export Recorded Data¤ to open context menu.

	Load Recorded Data	
	Save & Export Recorded Data	
~	Auto Scale	
	Setup Scale Values	
	Configure Recorder	
0	Help	F1

Figure 8-80 Save recorded Data

- 2) Select desired path.
- 3) Enter a file name.
- 4) Press ¤Save¤.

Save As	Disk (C:) • • • • •	Disk (C;)
Organize - New folder		8≣ ▼ 🔞
Local Disk (C) Abfall Batch CBB MyData MyProjects MySoftware oracle PerfLogs	Name Abfall Abfall Batch CB MyData MyMedia MySoftware oracle T	Date modifier 12.09.2012 10: E 05.07.2012 07: 27.07.2012 15: 30.07.8.2012 08: 29.08.2012 12: 03.08.2012 07: 04.07.2012 15: •
File name: myData Save as type: RecordedData Fil Hide Folders	es (*.rda) Save	Cancel

Figure 8-81 Save recorded Data

#### Data Recording

Example: Data Recording in "Profile Position Mode"



#### **Best Practice**

Save recorded data as ASCII text file or as bitmap!

#### 8.4.5 Step 5: Analyze recorded Data

- 1) Select cursor mode ¤Attached Cursor¤.
- 2) Tick ¤Position Actual Value¤ in "Available Curves".
- 3) Move cursor over the display and read the attached curve's values.



Figure 8-82 Analyze recorded Data

#### 8.4.6 Step 6: Restart Data Recorder

Click ¤Start¤ to restart and prepare the data recorder for the next recording.



Figure 8-83 Restart Data Recorder

# 8.5 Data Recorder Specifications

# 8.5.1 Functionalities

#### Recorder

- Executed in current regulator (max 10 kHz sampling rate)
- Configurable sampling rate
- Total buffer size: 512 words

While the data recorder is running, data are sampled to a ring buffer until a trigger is set. After a trigger, data will be recorded until the buffer is full.

#### Variables

- Max. four variables of the Object Dictionary
- 16-bit and 32-bit variables are allowed (one word)
- 8-bit variables need 16-bits in the data recorder memory

# Trigger

Following automatic trigger modes are supported:

- Manuel Trigger set by communication
- Movement Trigger set at movement start
- Error Trigger set by error
- Digital Input Trigger set by digital input
- End of Profile Trigger set at movement stop

# 8.5.2 Object Description

#### 8.5.2.1 Data Recorder Control

#### Description

The data recorder is controlled by write access.

Name	Data Recorder Control	
Index	0x2010	
Subindex	0x00	
Туре	UNSIGNED16	
Access	RW	
Default Value	0	
Value Range	0	3

Bit	Description
152	reserved
1	0 = no trigger 1 = force trigger
0	0 = stop recorder 1 = start recorder

Table 8-84

Data Recorder Control – Bits

#### Data Recording Data Recorder Specifications

# 8.5.2.2 Data Recorder Configuration

# Description

Configures the auto trigger functions.

Name	Data Recorder Configuration
Index	0x2011
Subindex	0x00
Туре	UNSIGNED16
Access	RW
Default Value	0
Value Range	→Table 8-85

Bit	Description
154	reserved
3	1 = trigger at end of profile
2	1 = trigger upon digital input
1	1 = trigger by error state
0	1 = trigger at movement start

Table 8-85Data Recorder Configuration – Bits

### 8.5.2.3 Data Recorder Sampling Period

#### Description

Sampling period as a multiple of the current regulator cycle (n multiplied by 0.1ms).

Name	Data Recorder Sampling Period		
Index	)x2012		
Subindex	0x00		
Туре	UNSIGNED16		
Access	RW		
Default Value	10		
Value Range	0	65535	

# 8.5.2.4 Data Recorder Number of Preceding Samples

## Description

Number of preceding samples defines the trigger position in the data recorder buffer.

Name	Data Recorder Number of Preceding Samples		
Index	)x2013		
Subindex	0x00		
Туре	UNSIGNED16		
Access	RW		
Default Value	0		
Value Range	0	65535	

# 8.5.2.5 Data Recorder Number of Sampling Variables

## Description

Number of variables (max. 4) to be recorded.

Name	Data Recorder Number of Sampling Variables		
Index	0x2014		
Subindex	0x00		
Туре	UNSIGNED16		
Access	RW		
Default Value	0		
Value Range	0	4	

# 8.5.2.6 Data Recorder Index of Variables

### Description

Index of Object Dictionary.

# **Related Objects**

→Data Recorder Subindex of Variables

Name	Data Recorder Index of Variables
Index	0x2015
Number of entries	0x05

Names	Data Recorder Index of Variable 1 Data Recorder Index of Variable 2	Data Recorder Index of Variable 3 Data Recorder Index of Variable 4
Index	0x2015	
Subindex	0x010x04	
Туре	UNSIGNED16	
Access	RW	
Default Value	0	
Value Range	→Object Dictionary	

#### Data Recording Data Recorder Specifications

# 8.5.2.7 Data Recorder Subindex of Variables

# Description

Subindex of Object Dictionary.

# **Related Objects**

→ Data Recorder Index of Variables

Name	Data Recorder Subindex of Variables
Index	0x2016
Number of entries	0x05

Names	Data Rec Subindex of Variable 1 Data Rec Subindex of Variable 2	Data Rec Subindex of Variable 3 Data Rec Subindex of Variable 4
Index	0x2016	
Subindex	0x010x04	
Туре	UNSIGNED16	
Access	RW	
Default Value	0	
Value Range	→Object Dictionary	

#### 8.5.2.8 Data Recorder Status

#### Description

Data recorder's status.

Name	Data Recorder Status
Index	0x2017
Subindex	0x00
Туре	UNSIGNED16
Access	RO
Default Value	0
Value Range	→Table 8-86

Bit	Description
152	reserved
1	0 = not triggered 1 = triggered
0	0 = stopped 1 = running

Table 8-86 Data Recorder Status – Bits

# 8.5.2.9 Data Recorder Max. Number of Samples

### Description

Defines maximal number of samples per variable. The parameter is dynamically calculated by the data recorder.

The maximal number of samples is the memory size (512 words) divided by the sum of the variable size (in words) of all configured variables.

Name	Data Recorder max. Number of Samples
Index	0x2018
Subindex	0x00
Туре	UNSIGNED16
Access	RO
Default Value	0
Value Range	

#### Example:

Sum of Variable Size [word]	Example	Number of Samples
1	1 x 16-bit variable or 1 x 8-bit variable	512
2	1 x 32-bit variable	256
3	1 x 16-bit and 1 x 32-bit variable	170
8	4 x 32-bit variables	64

Table 8-87Data Recorder Max. Number of Samples – Example

# 8.5.2.10 Data Recorder Number of recorded Samples

#### Description

Offset to the start of the recorded data vector within the ring buffer.

Data Recorder Number of recorded Samples
0x2019
0x00
UNSIGNED16
RO
0

#### Data Recording Data Recorder Specifications

### 8.5.2.11 Data Recorder Data Buffer

# Description

Memory for the different data recorder's ring buffers. Memory allocation is dynamically calculated when the recorder is started.

Name	Data Recorder Data Buffer
Index	0x201B
Subindex	0x00
Туре	Domain
Access	RO
Default Value	0
Value Range	

# Data Buffer Segmentation (Example: 2 x 16-bit variables, 1 x 32-bit variable)



StartRingBuffer1 = 0

StartRingBuffer2 = MaxNbOfSamples \* nbOfWords(Variable1)

StartRingBuffer3 = MaxNbOfSamples \* (nbOfWords(Variable1) + nbOfWords(Variable2)